Overview of Space

	Found- ation		Lower Primary		Middle Primary		Upper Primary		Lower Secondary	Middle Secondary
	 identify basic 2D shapes sort objects by shape 	• use number of sides to classify	• recognise sets and subsets of shapes	 identify both static and dynamic angles 	name and describe triangles and quadrilaterals	using thei • use mat language		 construct 21 using angle a properties use angle p polygons 	ind line	use angle properties of circles
	 identify basic 3D solids (e.g. boxes, balls) sort objects by shape 	• name spheres and cubes		• make prisms and pyramids from nets	• identify face edges, vertice use to classify	es and vie / • m dra	nterpret birds-eye w and elevations nake isometric awings of 3-D jects	 construct so to specification use single-prespective to simple object 	ooint o sketch a	 describe hidden surfaces and cross-sections of solids explore properties of spheres draw images (perspective & isometric)
	describe relative position (e.g. next to, below)	• recognise line symmetry and congruence	• transform shapes with flips, slides, turns & enlargement	 create simp tessellations solve geometry 			insformations to s te tessellations fro hapes)	om and si and so • relat	e similarity to gement from	 link algebraic and geometric transformations of graphs prove congruence or similarity
Location and scale	• use language of position	• identify features on maps (e.g. local creek)	give directions using left and right •construct simple local maps	 use map grid locate NESW by sun 	• give directions using grid references and compass directions	• interpret simple ma scales		 use precise map references use map symbols and contours 	bearings and Cartesian coordinates	 use latitude and longitude measure great circle distances
Networks			• interp	interpret simple netwo		 use network diagrams to s relationships and connection 			stigate	•find and interpret paths and circuits
	Found- ation		Lower Primary		Middle Primary		Upper Primary		Lower Secondary	Middle Secondary